

Hash Consing in JuliaSymbolics for Efficient Symbolic-Numeric Code Generation

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Abstract

We present a software contribution for JuliaSymbolics that adds transparent hash consing to the SymbolicUtils.jl term representation used by Symbolics.jl and ModelingToolkit.jl. Immutable `BasicSymbolic` compound terms are interned through weak-reference tables, turning repeated expression trees into shared directed acyclic graphs without changing the user API. On a 1,122-variable B cell receptor model, the implementation reduces Jacobian-construction memory by about $2\times$ and improves symbolic Jacobian time by about $3.2\times$. On XSteam-based thermodynamic benchmarks, generated-code compilation improves by nearly $10\times$ and numerical evaluation by $20\times$ – $100\times$, while low-repetition construction cases may pay lookup overhead.

1 Software contribution

The software contribution is a hash-consed term layer for JuliaSymbolics, the ecosystem around Symbolics.jl, SymbolicUtils.jl, and ModelingToolkit.jl [1, 2]. These packages support symbolic-numeric modeling, transformations of differential-algebraic systems, and compiled Julia kernels. The change is an infrastructure improvement: the same modeling code constructs a more compact internal representation.

Before this work, structurally equal subexpressions could be allocated repeatedly as distinct Julia objects. That tree-oriented representation is flexible, but it is costly in large symbolic-numeric workloads: memory pressure grows, equality tests traverse structure, and code generation must re-discover sharing lost during term construction. Our implementation makes live, structurally equal immutable expressions share one object, exposing a DAG while preserving Symbolics.jl syntax. Unlike conventional common-subexpression elimination, which discovers repetition after construction, hash consing prevents many duplicate objects from being allocated and makes sharing available to later passes.

2 Implementation

Hash consing, originating in work on arithmetic expressions and later Lisp and functional-language runtimes [3, 4, 5], queries a table whenever a compound immutable object is created. If a structurally equal object exists, the constructor returns it, saving memory and reducing equality of shared terms to pointer comparison.

In JuliaSymbolics the relevant construction path lives in `SymbolicUtils.jl` and the `TermInterface.jl` protocol [6, 7]. The interned units are immutable `BasicSymbolic` compound terms built through this path. Structurally, a term is its operator or head, ordered arguments, symtype/domain information, and relevant metadata after existing constructor-level simplifications. Leaf symbols, constants, and mutable or ad hoc objects are not the main target unless they pass through the same immutable constructor path; immutability makes it safe to return one representative object to multiple users.

The constructor hashes each compound term, looks it up in a weak-value table, and returns an existing canonical term or inserts a representative of its structural class. Weak values share live expressions without keeping obsolete objects alive forever [8, 9]. The implementation uses a global weak-value interning table for canonical representatives. In multithreaded contexts, task-local hash-consing caches and memoization tables support lock-free operation; identical work may still be duplicated across threads, so cross-thread caching of memoized results remains a future optimization.

Hash consing detects structural equality of the internal representation, not arbitrary mathematical equivalence. Thus $x^0 \cdot y^2$, y^2 , and $y^2 \cdot z^0$ share only if existing normalization reduces them to the same structural term, such as y^2 ; the hash table does not prove equivalence. Hash values are cached on terms, and collisions fall back to structural checks, so the table is an accelerator rather than a soundness assumption.

Hash consing alone is not enough: tree-oriented algorithms can still revisit a shared subterm many times. We therefore adapted code generation to track visited shared terms, emit temporary bindings, and preserve evaluation order. For instance, in $(x+y)^2 + \sin(x+y)$, both $x+y$ occurrences can share the same representative, letting code generation emit `t1 = x + y` and reuse `t1` instead of recomputing the subterm.

3 Demonstration and evaluation

The presentation will construct repeated `Symbolics.jl` expressions, show the temporaries introduced for shared DAG nodes, and report benchmark results for two scientific-modeling workloads: a B cell receptor signaling model with 1,122 ODEs and 24,388 reactions [10], and symbolic thermodynamic models derived from `XSteam.jl` and the IAPWS-IF97 water-steam formulation [11, 12]. The live example establishes the invariant that repeated terms become shared nodes; the benchmarks show effects on memory, generated code size, compilation latency, and evaluation time.

The reported measurements were run on Ubuntu Linux (kernel 5.15.0-58-generic) on x86_64 with an AMD EPYC 7502 32-core processor, Julia 1.10.9, `SymbolicUtils.jl` 3.25.1, and `Symbolics.jl` 6.36.0. We measure wall-clock time and allocated memory for symbolic Jacobian construction, code generation, compilation, and numerical evaluation through ordinary `Symbolics.jl` and `ModelingToolkit.jl` construction paths. Benchmarks used `SymbolicUtils.jl` 3.25.1; the documentation citation refers to public documentation for the same `TermInterface`/`SymbolicUtils` concepts accessed during

manuscript preparation.

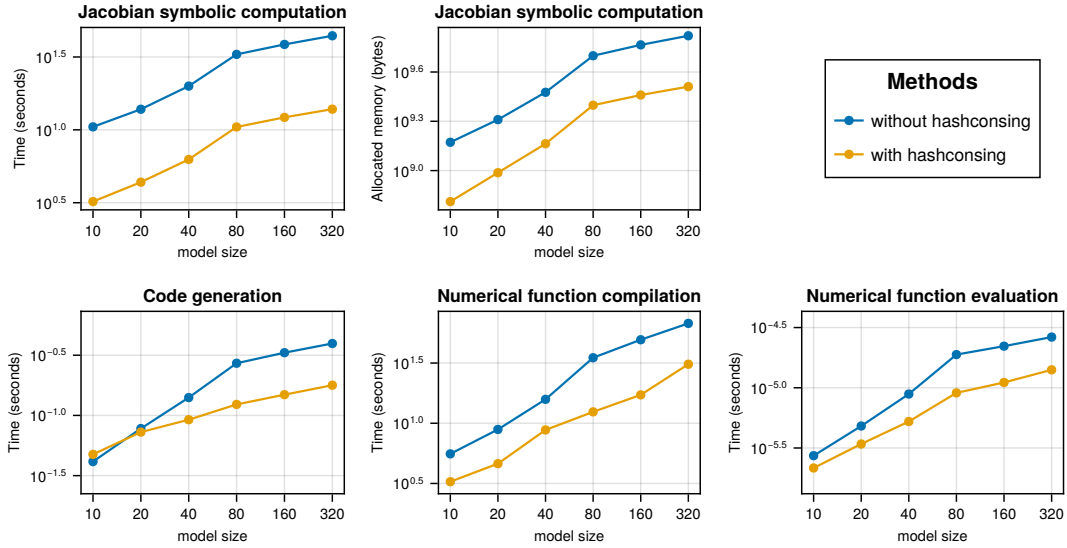


Figure 1: BCR benchmark results. Representative BCR and XSteam takeaways are summarized in Table 1.

Table 1: Representative effects of hash consing and DAG-aware code generation.

Workload or regime	Representative effect
BCR Jacobian construction	About $2\times$ less memory and about $3.2\times$ faster symbolic Jacobian construction
XSteam-generated numerical code	Nearly $10\times$ generated-code compilation improvement and $20\times$ – $100\times$ numerical evaluation speedup
Low-repetition construction	Lookup overhead can dominate before downstream DAG-aware passes exploit sharing

The mixed behavior is informative. Reaction-network Jacobians contain repeated local motifs, so construction-time interning helps Jacobian construction and memory immediately. XSteam-derived formulas may expose fewer duplicate unknown-variable terms during initial construction, so early Jacobian gains can be smaller or overhead can appear. Yet generated numerical programs contain repeated expensive thermodynamic fragments, so DAG-aware code generation reduces compiled code size, compilation latency, and evaluation work. Users should evaluate the whole symbolic-to-numeric pipeline, not only construction time.

There are also clear limitations. Hash consing is most attractive for immutable terms created through centralized constructors; mutable or ad hoc construction requires extra invalidation or normalization machinery. Weak references prevent unbounded table growth, but lookup cost can dominate when few repeated terms are produced; adaptive policies based on expression size, operator distribution, or observed hit rate are natural future work.

4 Related software

Other computer algebra systems expose related representation questions; for example, Symbolica reached a 1.0 release as a high-performance Rust and Python library [13]. Hash consing is also complementary to e-graph rewriting: e-graphs represent equivalence classes of expressions, whereas hash consing canonicalizes structurally identical terms. Combining hash-consed sharing with equality-saturation techniques relevant to JuliaSymbolics is a natural next development [14].

5 Conclusion

The presented software contribution is a transparent hash-consed representation for JuliaSymbolics terms, together with DAG-aware code generation and benchmark evidence on large scientific models. The main lesson is that maximal sharing is most valuable when downstream symbolic-numeric stages exploit it explicitly. The result is a concrete implementation in an active symbolic computation ecosystem that improves performance on representative workloads and exposes practical design tradeoffs for future symbolic software.

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